# FPT results through potential maximal cliques 

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## Minimal separators



Definition
$S \subseteq V$ is a minimal
$a, b$-separator if $S$ separates $a$ and $b$ and it is inclusion-minimal for this property.

Definition
$S$ is a minimal separator of $G$ there exist vertices $a, b$ s.t. $S$ is a minimal $a, b$-separator.

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## Potential maximal cliques

## Definition

A set of vertices $\Omega$ is a potential maximal clique of $G$ if is a maximal clique in some minimal triangulation of $G$.

## Proposition (Bouchitté, Todinca 2001)

The number of potential maximal cliques is polynomial in the number of minimal separators.

## Minimal separators and $\mathcal{G}_{\text {poly }}$

## Definition

For a polynomial poly, let $\mathcal{G}_{\text {poly }}$ be the class of graphs such that $G \in \mathcal{G}_{\text {poly }}$ if $G$ has at most poly $(n)$ minimal separators.
Class $\quad$ minimal separators $\quad$ potential maximal cliques

| Weakly chordal | $\mathcal{O}\left(n^{2}\right)$ | $\mathcal{O}\left(n^{2}\right)$ |
| :---: | :---: | :---: |
| Chordal | $\mathcal{O}(n)$ | $\mathcal{O}(n)$ |
| Polygon-circle | $\mathcal{O}\left(n^{2}\right)$ | $\mathcal{O}\left(n^{3}\right)$ |
| Circle | $\mathcal{O}\left(n^{2}\right)$ | $\mathcal{O}\left(n^{3}\right)$ |
| Circular arc | $\mathcal{O}\left(n^{2}\right)$ | $\mathcal{O}\left(n^{3}\right)$ |
| $d$-trapezoid | $\mathcal{O}\left(n^{d}\right)$ | $\mathcal{O}\left(n^{d+2}\right)$ |

When the input graph belongs to $\mathcal{G}_{\text {poly }}$ we can find in polynomial time a Maximum Induced:

- Independent Set, Forest, Path, Matching
- Subgraph With no cycles $\geq I$, Outerplanar
- Subgraph With no cycles of length 0 mod $/$

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For $t \geq 0$ and $\mathcal{P}$ a CMSO property:
Optimal Induced Subgraph for $\mathcal{P}$ and $t$
Input: A graph $G=(V, E)$
Output A largest induced subgraph $G[F]$ s.t.

- $t w(G[F]) \leq t$,
- $G[F]$ satisfies $\mathcal{P}$.

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Theorem (Fomin, Todinca, Villanger, 2015)
Optimal Induced Subgraph for $\mathcal{P}$ and $t$ on $\mathcal{G}_{\text {poly }}$ is solvable in polynomial time.

When the input graph belongs to $\mathcal{G}_{\text {poly }}$ we can find in polynomial time a Maximum Induced:

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Theorem (Fomin, Todinca, Villanger, 2015)
Optimal Induced Subgraph for $\mathcal{P}$ and $t$ is solvable time $\mathcal{O}\left(\#\right.$ Potential maximal cliques $\left.\cdot n^{t+c s t} \cdot f(\mathcal{P}, t)\right)$.

## In this talk, two extensions:

1) Theorem (Fomin, Liedloff, M., Todinca. SWAT 2014) Optimal Induced Subgraph for $\mathcal{P}$ and $t$ can be solved in time $\mathcal{O}^{*}\left(4^{\text {vc }}\right)$ and $\mathcal{O}^{*}\left(1.7347^{\mathrm{mw}}\right)$.
2) Definition $\left(\mathcal{G}_{\text {poly }}+k v\right)$
$G \in \mathcal{G}_{\text {poly }}+k v$ if there exists a set $M \subset V$ called modulator, $|M| \leq k$ s.t. $G-M \in \mathcal{G}_{\text {poly }}$.

Theorem (Liedloff, M. and Todinca. WG 2015)
Optimal Induced Subgraph for $\mathcal{P}$ and $t$ on $\mathcal{G}_{\text {poly }}+k v$ with parameter $k$ is fixed-parameter tractable, when the modulator is also part of the input.

## First result

Theorem (Fomin, Todinca, Villanger, 2015)
Optimal Induced Subgraph for $\mathcal{P}$ and $t$ is solvable time $\mathcal{O}\left(\#\right.$ Potential maximal cliques $\left.\cdot n^{t+c s t} \cdot f(\mathcal{P}, t)\right)$.

Our result:
Theorem
The number of potential maximal cliques is bounded by

- $\mathcal{O}^{*}\left(4^{v c}\right)$
- $\mathcal{O}^{*}\left(1.7347^{\mathrm{mw}}\right)$


## Vertex cover

## Definition

The vertex cover of a graph $G$, denoted by $\mathrm{vc}(G)$, is the minimum number of vertices that cover all edges of the graph.


- The number of minimal separators is bounded by $3^{\mathrm{vc}}$
- The number of potential maximal cliques is bounded by $\mathcal{O}^{*}\left(4^{v c}\right)$


## Vertex cover and minimal separators



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## Vertex cover and minimal separators



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## Vertex cover and minimal separators

For any vertex cover $W$

$$
S \rightarrow\left(S^{W}, D_{1}, D_{2}\right)=W
$$

$$
S=S^{W} \cup\left\{x \in V \backslash W \mid N(x) \text { intersects both } D_{1} \text { and } D_{2}\right\}
$$

## Vertex cover and minimal separators

For any vertex cover $W$

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\begin{gathered}
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\end{gathered}
$$

Theorem

- Number of minimal separators is $\mathcal{O}\left(3^{\mathrm{vc}}\right)$
- They can be listed in time $\mathcal{O}^{*}\left(3^{\mathrm{vc}}\right)$


## Potential maximal cliques and minimal separators

Potential maximal cliques and minimal separators


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## Potential maximal cliques and minimal separators



## Potential maximal cliques and minimal separators



## Vertex cover and pmc



## Vertex cover and pmc



## Vertex cover and pmc



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## Vertex cover and pmc



## Vertex cover and pmc

For any vertex cover $W$

$$
\Omega \rightarrow\left(\Omega^{W}, D_{R}, D_{U}, D_{L}\right)=W
$$

$\Omega=\Omega^{W}$
$\cup\left\{x \in V \backslash W \mid N(x)\right.$ intersects both $D_{R}$ and $\left.\left(D_{U} \cup D_{L}\right)\right\}$
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$$

Theorem

- Number of potential maximal cliques is $\mathcal{O}^{*}\left(4^{\mathrm{vc}}\right)$
- They can be listed in time $\mathcal{O}^{*}\left(4^{\mathrm{vc}}\right)$


## Modular width

## Definition

The modular width $\mathrm{mw}(G)$ can be defined as the maximum degree of a prime node in the modular decomposition tree of $G$


- The number of minimal separators is bounded by $\mathcal{O}^{*}\left(1.6181^{\mathrm{mw}}\right)$,
- The number of potential maximal cliques is bounded by $\mathcal{O}^{*}\left(1.7347^{\mathrm{mw}}\right)$.


## Modular width and minimal separators



G


## Modular width and minimal separators



G


## Modular width and minimal separators



G


## Modular width and minimal separators



Theorem (Fomin, Villanger (2010))
Every n-vertex graph has $\mathcal{O}\left(1.6181^{n}\right)$ minimal separators and $\mathcal{O}\left(1.7347^{n}\right)$ potential maximal cliques.

## Conclusion

Theorem
Optimal Induced Subgraph for $\mathcal{P}$ and $t$ can be solved in time $\mathcal{O}^{*}\left(4^{v c}\right)$ and $\mathcal{O}^{*}\left(1.7347^{\mathrm{mw}}\right)$

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Optimal Induced Subgraph for $\mathcal{P}$ and $t$ can be solved in time $\mathcal{O}^{*}\left(4^{v c}\right)$ and $\mathcal{O}^{*}\left(1.7347^{\mathrm{mw}}\right)$

Also..

- (Weighted) Treewidth,
- (Weighted) Minimum fill in,
- Treelength.

Are solvable in time $\mathcal{O}^{*}(\# \mathrm{pmc})$ ([Gysel], [Lokshtanov],..)

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Are solvable in time $\mathcal{O}^{*}(\# \mathrm{pmc})$ ([Gysel], [Lokshtanov],..) (then in time $\mathcal{O}^{*}\left(4^{\mathrm{vc}}\right)$ and $\mathcal{O}^{*}\left(1.7347^{\mathrm{mw}}\right)$ ).

- Running times that are single exponential in the parameter.
- This result covers both sparse and dense families of graphs.




## Second result

Definition $\left(\mathcal{G}_{\text {poly }}+k v\right)$
$G \in \mathcal{G}_{\text {poly }}+k v$ if there exists a set $M \subset V$ called modulator, $|M| \leq k$ s.t. $G-M \in \mathcal{G}_{\text {poly }}$.

Theorem (Liedloff, M. and Todinca. WG 2015)
Optimal Induced Subgraph for $\mathcal{P}$ and $t$ on $\mathcal{G}_{\text {poly }}+k v$ with parameter $k$ is fixed-parameter tractable, when the modulator is also part of the input.

## The tools

- Tools from [Fomin, Villanger, 2010] and [Fomin, Todinca, Villanger, 2015] for computing a Maximum induced subgraph of TREEWIDTH $t$ :
- Decompositions with minimal separators.
- Potential maximal cliques
- Dynamic programming over all minimal tree decompositions of the input graphs, using potential maximal cliques.
- Results [Bodlaender, Kloks, 1996]
- Given a graph $G$ and a tree decomposition of width at most $k+t$, determine if $G$ has treewidth $t$ in time $\mathcal{O}(f(t+k) n)$,



## Decomposing with minimal separators



## Decomposing with minimal separators



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## Decomposing with minimal separators



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## Decomposing with minimal separators



## Decomposing with minimal separators


g
h

## Decomposing with minimal separators



- $\begin{aligned} & g \\ & h\end{aligned}$


## Decomposing with minimal separators



- $\begin{aligned} & g \\ & h\end{aligned}$


## Decomposing with minimal separators



Theorem (Parra, Schaeffler 97)
Decomposing through minimal separators $\rightarrow$ minimal tree decompositions.

## Potential maximal cliques

Definition
A set of vertices $\Omega$ is a potential maximal clique of $G$ if is a maximal clique in some minimal triangulation of $G$.

## Definition

A set of vertices $\Omega$ is a potential maximal clique of $G$ if there is a minimal tree decomposition $T G$ of $G$ such that $\Omega$ is a bag in $T G$.

## Proposition (Bouchitté, Todinca 2001)

The number of potential maximal cliques is polynomial in the number of minimal separators.

## Dynamic programming over minimal separators...

MAXIMUM INDUCED SUBGRAPH OF TREEWIDTH $t$ ON $\mathcal{G}_{\text {poly }}$
$S$ : minimal separator of $G$
$C$ : component of $G-S$
$T$ : a subset of $S$ of size $\leq t+1$
$O P T(S, C, T)$ the size of the largest partial solution $G[F]$ s.t.

- $F \subseteq S \cup C$
- $T=F \cap S$

C


## Dynamic programming over minimal separators...

MAximum induced subgraph of Treewidth $t$ ON $\mathcal{G}_{p o l y}$
$S$ : minimal separator of $G$
$C$ : component of $G-S$
$T$ : a subset of $S$ of size $\leq t+1$
OPT $(S, C, T)$ the size of the largest partial solution $G[F]$ s.t.

- $F \subseteq S \cup C$
- $T=F \cap S$



## ....and potential maximal cliques



$$
O P T(S, C, T):
$$

## ....and potential maximal cliques



## OPT(S, C, T):

- guess the potential maximal clique $\Omega$ splitting $S \cup C$


## ....and potential maximal cliques



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O P T(S, C, T):
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## ....and potential maximal cliques


$\operatorname{OPT}(S, C, T)$ :

- guess the potential maximal clique $\Omega$ splitting $S \cup C$
- and $T \subseteq T^{\prime}$ the bag of $F$ that intersects $\Omega$,

$$
\left|T^{\prime}\right| \leq t+1
$$

....and potential maximal cliques


$$
\text { OPT }(S, C, T):
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$$
\left|T^{\prime}\right| \leq t+1
$$

$\operatorname{OPT}\left(S_{1}, C_{1}, T^{\prime} \cap S_{1}\right)+O P T\left(S_{2}, C_{2}, T^{\prime} \cap S_{2}\right)+\left|T^{\prime} \backslash\left\{S_{1} \cup S_{2}\right\}\right|$


$$
O P T(S, C, T):
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- guess the potential maximal clique $\Omega$ splitting $S \cup C$
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$$

$$
\begin{aligned}
\operatorname{OPT}(S, C, T)= & \max ^{S \subset \Omega \subset C \cup S, T \subset T^{\prime} \subset \Omega}\left(O P T\left(S_{1}, C_{1}, T^{\prime} \cap S_{1}\right)\right. \\
& \left.+O P T\left(S_{2}, C_{2}, T^{\prime} \cap S_{2}\right)+\left|T^{\prime} \backslash\left\{S_{1} \cup S_{2}\right\}\right|\right)
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O P T(S, C, T):
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- guess the potential maximal clique $\Omega$ splitting $S \cup C$
- and $T \subseteq T^{\prime}$ the bag of $F$ that intersects $\Omega$, $\left|T^{\prime}\right| \leq t+1$.

$$
\begin{aligned}
\operatorname{OPT}(S, C, T)= & \max ^{\operatorname{S\subset \Omega \subset C\cup S,T\subset T^{\prime }\subset \Omega }\left(O P T\left(S_{1}, C_{1}, T^{\prime} \cap S_{1}\right)\right.} \\
& \left.+O P T\left(S_{2}, C_{2}, T^{\prime} \cap S_{2}\right)+\left|T^{\prime} \backslash\left\{S_{1} \cup S_{2}\right\}\right|\right)
\end{aligned}
$$

Running time: $O$ ( $n^{t+c s t .}$ \#potential maximal cliques) Key lemma [Fomin, Villanger 2010]: we don't miss solutions.

## Dynamic programming over minimal separators...

Maximum induced subgraph of treewidth $t$ on $\mathcal{G}_{\text {poly }}+k v$
$F^{M}$ : A subset of the modulator of size $k^{\prime}$.


S: minimal separator of $G^{\prime}$
$C$ : component of $G^{\prime}-S$
$T$ : a subset of $S$ of size $\leq t+1$
OPT $(S, C, T)$ the size of the largest partial solution $G[F]$ s.t.

- $F^{M}=F \cap M$
- $F \backslash M \subseteq S \cup C$
- $T=F \cap S$


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This way we build a tree decomposition of $G[F]$ of width $\leq t+k^{\prime}$
[Bodlaender, Kloks, 1996]:

- Algorithm that takes as input a graph with a tree decomposition of width at most $t+k$ and decides if this graph has treewidth $t$ in time $\mathcal{O}(f(t+k) n)$, with $f(x)=2^{\mathcal{O}\left(x^{3} \log (x)\right)}$
[Bodlaender, Kloks, 1996]:
- Algorithm that takes as input a graph with a tree decomposition of width at most $t+k$ and decides if this graph has treewidth $t$ in time $\mathcal{O}(f(t+k) n)$, with $f(x)=2^{\mathcal{O}\left(x^{3} \log (x)\right)}$
- Full set of characteristics: Set of constant size that encodes the decision in a partial solution
[Bodlaender, Kloks, 1996]:
- Algorithm that takes as input a graph with a tree decomposition of width at most $t+k$ and decides if this graph has treewidth $t$ in time $\mathcal{O}(f(t+k) n)$, with $f(x)=2^{\mathcal{O}\left(x^{3} \log (x)\right)}$
- Full set of characteristics: Set of constant size that encodes the decision in a partial solution
- if two partial solutions are glued, then the characteristic of the resulting graph can be computed from the characteristics of each part.


## Dynamic programming over minimal separators...

$F^{M}$ : A subset of the modulator of size $k^{\prime}$.
S: minimal separator of $G^{\prime}$
$C$ : component of $G^{\prime}-S$
$T$ : a subset of $S$ of size $\leq t+1$
c: a characteristic of $(\operatorname{tw}(G) \leq t)$
OPT $(S, C, T, c)$ the size of the largest partial solution $G[F]$ s.t.

- $F^{M}=F \cap M$
- $F \backslash M \subseteq S \cup C$
- $T=F \cap S,|T| \leq t$

- $G[F]$ has characteristic $c$


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Running time: $O\left(n^{t+c s t} \cdot f(t+k)\right.$. \#potential maximal cliques)

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$C$ : component of $G^{\prime}-S$
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$c$ : a characteristic of $(\operatorname{tw}(G) \leq t) \wedge \mathcal{P}$
OPT $(S, C, T, c)$ the size of the largest partial solution $G[F]$ s.t.

- $F^{M}=F \cap M$
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- $T=F \cap S,|T| \leq t$

- $G[F]$ has characteristic $c$

Running time: $O\left(n^{t+c s t} \cdot f(t+k, \mathcal{P}) \cdot\right.$ \#potential maximal cliques)

## To sum up

## Theorem

Optimal Induced Subgraph for $\mathcal{P}$ and $t$ on $\mathcal{G}_{\text {poly }}+k v$ is solvable in time $\mathcal{O}\left(n^{t} \cdot p o l y^{\prime}(n) \cdot f(t+k, \mathcal{P})\right)$ when the modulator is also part of the input.

| $t$ | $\mathcal{P}$ | $f$ |
| :---: | :---: | :---: |
| any | any | tower of exponentials |
| any | none | $2^{\mathcal{O}\left((t+k)^{3} \log (t+k)\right)}$ |
| 0 | none | $2^{\mathcal{O}(k)}$ |
| 1 | none | $2^{\mathcal{O}(k \log (k))}$ |

## To sum up

## Theorem

Optimal Induced Subgraph for $\mathcal{P}$ and $t$ on $\mathcal{G}_{\text {poly }}+k v$ is solvable in time $\mathcal{O}\left(n^{t} \cdot\right.$ poly $\left.^{\prime}(n) \cdot f(t+k, \mathcal{P})\right)$ when the modulator is also part of the input.

| $t$ | $\mathcal{P}$ | $f$ |
| :---: | :---: | :---: |
| any | any | tower of exponentials |
| any | be connected | $2^{\mathcal{O}\left((t+k)^{3} \log (t+k)\right)}$ |
| 0 | none | $2^{\mathcal{O}(k)}$ |
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## Discussion

What if the modulator is not a part of the input?

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Deletion to $\mathcal{G}_{\text {poly }}$
Input: A graph $G=(V, E)$ and a constant $k$
Parameter: $k$
Output: A set $M \subseteq V$ of size at most $k$ s.t. $G-M$ belongs to $\mathcal{G}_{\text {poly }}$.

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[Heggernes, van't Hof, Jansen, Kratsch, Villanger, 2013]

- Weakly chordal $+k v$ is $W[2]$-Hard
[Cao, Marx, 2014]
- Chordal $+k v$ is FPT


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