

Well-Structured Modulators: FPT Algorithms and Kernels

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Introduction

- ▶ General goal: identify conditions which allow solution of NP-hard graph problems
- ▶ We want to get results for a wide range of problems
- ▶ Many problems can be captured by **Monadic Second Order** (MSO) logic

MSO (MS_1) logic

- ▶ used in Courcelle's Theorem (no edge quantification)
- ▶ Quantify over vertices and vertex sets
- ▶ Atoms: edges between vertices, set inclusion, equality
- ▶ Example: $\exists x \forall y : edge(x, y) \vee x = y$.

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Expressible problems

- ▶ 3-colorability, 3-clique cover, 3-partition into trees ...
- ▶ $\exists A, B, C \forall x, y : partition$ and *neighborhood* conditions

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Definition ($MSO-MC_\varphi$)

Instance: A graph G .

Question: Does $G \models \varphi$ hold?

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Definition ($MSO-OPT_\varphi$)

Instance: A graph G and an integer r .

Question: Is there $X \subseteq V(G)$ s.t. $G \models \varphi(X)$ and $|X| \leq r$?

Structural approach

- ▶ MSO model checking NP-hard in general
...but efficiently solvable by using the structure of inputs

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...but efficiently solvable by using the structure of inputs
- ▶ How to measure the “structure” of inputs? →
Parameterized Complexity
- ▶ Idea: use a parameter k to measure how
“well-structured” the graph is
 - ▶ smaller k = more structured
- ▶ Develop algorithms which run well if the parameter is small
 - ▶ FPT algorithms: $f(k) \cdot n^{\mathcal{O}(1)}$ runtime
 - ▶ Kernelization: see later

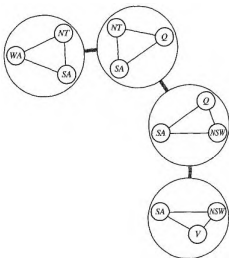
Choice of parameter

- ▶ A good parameter should
 - ▶ be *small* for as many inputs as possible, but
 - ▶ allow the design of FPT algorithms for many problems
- ▶ Two different approaches to parameter design:
 - ▶ Decompositions
 - ▶ Modulators

Decomposition approach

Parameters are associated with a *decomposition* which can be used to solve problems.

- ▶ Treewidth



Theorem (Courcelle)

For an n -vertex graph G with treewidth k and an MSO sentence φ , we can solve MSO-MC_φ in time $f(k, \varphi) \cdot n$.

- ▶ treewidth large on dense graphs

Decomposition approach

- ▶ Clique-width
 - ▶ more general than treewidth, low on some dense graphs
 - ▶ allows FPT-time MSO model checking if decompositions are provided
 - ▶ cannot compute decompositions

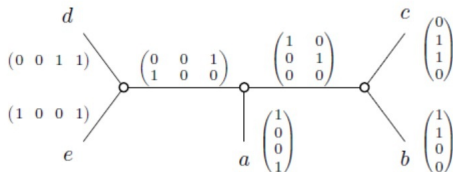
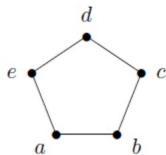
Decomposition approach

- ▶ Rank-width

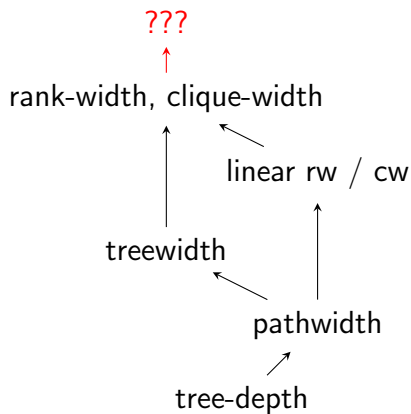
Theorem (Ganian, Hliněný)

For an n -vertex graph G with rank-width k and an MSO sentence φ , we can solve MSO-MC_φ in time $f(k, \varphi) \cdot n^3$.

- ▶ as general as clique-width—bounded from below and above by a function of clique-width
- ▶ can compute decompositions [Hliněný, Oum]



Decomposition-based width measures



Modulator approach

Parameters measure how “close” a graph is to a graph class \mathcal{H}

Also very successful in related fields (backdoors in SAT, CSP...)

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Also very successful in related fields (backdoors in SAT, CSP...)

- ▶ k is the number of vertices that need to be deleted to get to \mathcal{H}
- ▶ **Vertex Cover** and **Feedback Vertex Set** are special cases of modulators
- ▶ allow the use of a vast range of work on specific graph classes

This talk

Combine the 2 approaches to introduce a family of “hybrid” parameters.

Goal for FPT algorithms:

- ▶ more general than rank-width and modulators

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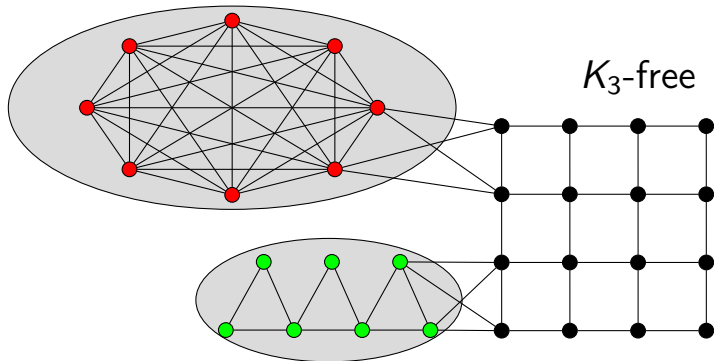
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Goal for FPT algorithms:

- ▶ more general than rank-width and modulators
- ▶ computable in FPT time
- ▶ allow FPT-time MSO model checking
 - ▶ under certain conditions...

Well-structured modulators

Basic idea: what if the graph has a large but **well-structured** modulator to \mathcal{H} ?



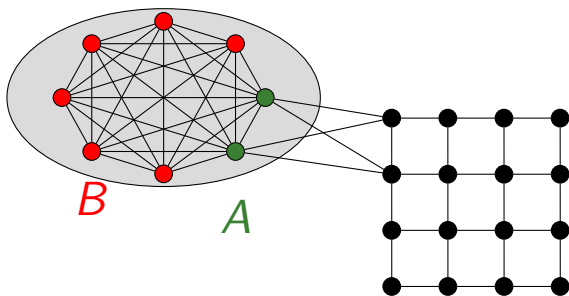
A graph with a 2-well-structured modulator to K_3 -free graphs

!!!Edges going into modulator **must** be controlled!!!

Well-structured modulators

We use **splits** to control edges going into the modulator.

A set of vertices $X \subseteq V(G)$ is a **split-module** if it can be partitioned into $\{A, B\}$ such that A is completely connected to neighborhood of X and B does not have neighbors outside X .

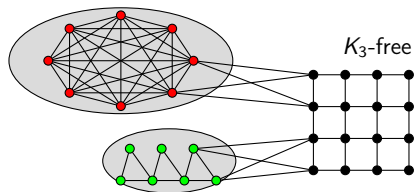


Well-structured modulators

Definition

A set \mathbf{X} of pairwise-disjoint split-modules of a graph G is called a k -well-structured modulator to \mathcal{H} if

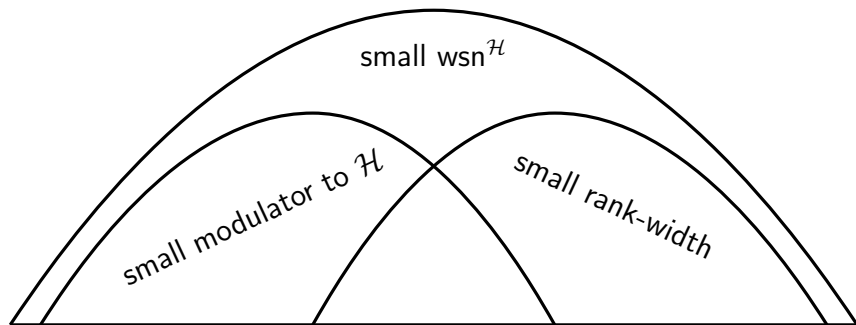
- ▶ $|\mathbf{X}| \leq k$, and
- ▶ $\bigcup_{X_i \in \mathbf{X}} X_i$ is a modulator to \mathcal{H} , and
- ▶ rank-width of $G[X_i] \leq k$ for each $X_i \in \mathbf{X}$.



A graph with a 2-well-structured modulator to K_3 -free graphs

Well-structured modulators vs. other parameters

Well-structure number ($\text{wsn}^{\mathcal{H}}$): minimum k such that G has a k -well-structured modulator to \mathcal{H}



Finding well-structured modulators

Theorem

Finding a k -well-structured modulator to any \mathcal{H} characterizable by a finite set of forbidden induced subgraphs is FPT.

Examples for \mathcal{H} : split graphs, P_5 -free graphs, graphs of bounded degree, triangle-free graphs, claw-free graphs. . .

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How this works:

- ▶ We use [Cunningham, 1982] and algorithm of [Gioan, Paul, Tedder, Corneil, 2014] to partition vertices into maximal split-modules of rank-width at most k .
- ▶ Reduce to d -hitting set.

Solving MSO-MC $_{\varphi}$

Theorem

For any MSO formula φ such that MSO-MC $_{\varphi}$ is FPT parameterized by modulator-size to \mathcal{H} , MSO-MC $_{\varphi}$ is FPT parameterized by $wsn^{\mathcal{H}}(G)$.

Blue part is a necessary condition.

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Note that this captures not only the generality of MSO-MC $_{\varphi}$, but also applies to many choices of \mathcal{H} .

MSO-MC _{φ} – Example

c -COLORING is FPT parameterized by the size of a modulator to P_5 -free graphs. [Golovach, Paulusma, Song 2014 + Cai 2003]

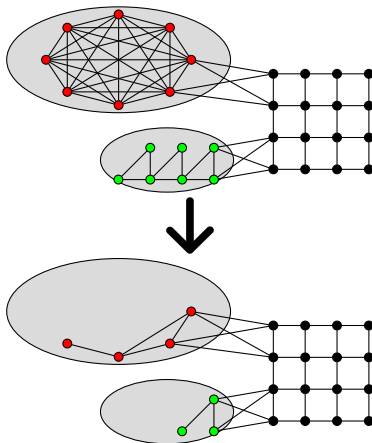
Hence:

Corollary

c -COLORING is FPT parameterized by $wsn^{P_5\text{-free}}$.

Solving MSO-MC _{φ} – Proof

Idea: replace big split-modules by small ones



Now use **necessary condition**

What about MSO-OPT_φ ?

Surprisingly, there is a (provable) difference in difficulty between MSO-OPT_φ and MSO-MC_φ par. by wsn .

Theorem

There exists an MSO formula φ and graph class \mathcal{H} (satisfying same conditions as for previous theorem) such that MSO-OPT_φ is paraNP-hard parameterized by $\text{wsn}^{\mathcal{H}}$.

Solving other problems

Theorem

MINIMUM VERTEX COVER *and* MAXIMUM CLIQUE are FPT parameterized by $wsn^{\mathcal{H}}$ iff they are polytime tractable on \mathcal{H} .

Weaker necessary condition – not sufficient for MSO-MC $_{\varphi}$!

Choices of \mathcal{H} for MINIMUM VERTEX COVER:

- ▶ $(2K_2, C_4, C_5)$ -free graphs (split graphs);
- ▶ P_5 -free graphs [Lokshtanov, Vatshelle, Villanger, 2014];
- ▶ fork-free graphs [Alekseev, 2004];
- ▶ (banner, $T_{2,2,2}$)-free graphs and (banner, $K_{3,3}$ -e, twin-house)-free graphs [Gerber, Brandstadt, Lozin, 2001-2003].

Kernelization

Kernelization studies the efficient preprocessing and compression of inputs.

Basic idea:

- ▶ A *kernelization algorithm* \mathbb{A} takes an instance (I, p) and outputs an instance (I', p') (the *kernel*) such that:
 - ▶ \mathbb{A} runs in polynomial time,
 - ▶ $(I, p) \in P$ iff $(I', p') \in P$, and
 - ▶ $|I'| + p' \leq f(p)$ for a (fixed) computable function f .

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If f is a polynomial function, then we speak of *polynomial kernels* – these are of particular interest.

Well-Structured Modulators for Kernelization

No polykernels when using rank-width.

!BUT! Modulators often give polykernels for various problems.

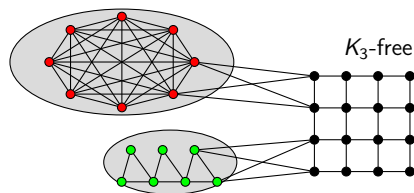
Can we exploit structure of modulators also for kernels?

(k, c) -Well-Structured Modulators

Definition

A set \mathbf{X} of pairwise-disjoint split-modules of a graph G is called a (k, c) -**well-structured modulator** (wsm) to \mathcal{H} if

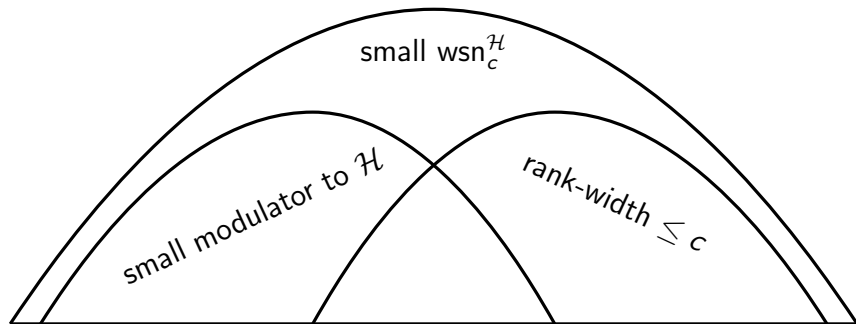
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A graph with a $(2, 1)$ -wsm to K_3 -free graphs

Well-structured modulators vs. other parameters

Well-structure number ($\text{wsn}_c^{\mathcal{H}}$): minimum k such that G has a (k, c) -well-structured modulator to \mathcal{H}



- ▶ [MFCS 2013]: special case of $\text{wsn}_c^{\mathcal{H}}$, where \mathcal{H} is empty and there are additional restrictions on split-modules.
- ▶ [Brno+Aachen, ESA 2013]: special case of $\text{wsn}_c^{\mathcal{H}}$, where bags have size 1 and \mathcal{H} is the class of constant treedepth.

WSMs for kernels

Differences compared to FPT algorithms:

- ▶ Finding WSMs for kernels
 - ▶ need to approximate in polytime (can't afford FPT time)

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- ▶ Using WSMs for kernels
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Theorem

For every MSO sentence φ and every graph class \mathcal{H} such that

- 1 MSO-MC $_{\varphi}$ admits a polykernel par. by modulator-size to \mathcal{H} , and*
- 2 a (k, c) -wsm to \mathcal{H} can be (poly)-approximated in polytime,*

MSO-MC $_{\varphi}$ admits a polykernel.

WSMs for kernels – applications

- ▶ If \mathcal{H} is the class of **empty graphs**, we lift our previous kernelization results of [MFCS 2013] and our main theorem also holds for MSO-OPT_φ .

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- ▶ If \mathcal{H} is the class of **edgeless graphs**, we lift vertex cover as a parameter. On graphs of bounded expansion, **every** MSO-MC_φ and MSO-OPT_φ problem admits a polykernel for $\text{wsn}_c^{\mathcal{H}}$.

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- ▶ If \mathcal{H} is a class of **bounded treedepth**, we lift previous results of [Aachen+Brno, ESA2013]. **Every** MSO-MC_φ problem admits a linear kernel parameterized by $\text{wsn}_c^{\mathcal{H}}$ on graphs of **bounded expansion**.

Final remarks

We introduced a family of “hybrid” parameters that:

- ▶ are more general than modulator-size (**and rank-width**)
- ▶ are approximable in polytime (**computable in FPT time**)
- ▶ allow kernelization (**FPT algorithms**) for MSO decision problems
 - ▶ under certain conditions

What else lies above rank-width?

Can we replace splits with less restrictive conditions?

Thank you for your attention!

